

Image Based Leaf Area Measurement Method Using Artificial Neural Network

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Abstract—Leaf area is an important parameter in plant monitoring. An automatic method for measuring leaf area is needed to obtain accurate result. In this paper, a method for automatic leaf area measurement from image is proposed. The method captured the image of leaf without object reference. Four features were extracted from the image and used as input to artificial neural network for estimating leaf area. The experiment results show that the proposed method can measure leaf area with mean absolute relative error less than 1% and less computational time.

Keywords—leaf area measurement, automatic, artificial neural network, image processing

I. INTRODUCTION

Leaf area plays an important role in plant monitoring, including monitoring plant growth, plant competition, and plant yield [1]. Moreover, leaf area can be used to measure the performance of mechanism occurred in a plant [2]. Traditionally, leaf area measurement can be performed manually using grid counting method [3-5] or paper weighing method [1]. These methods are simple in practice but time consuming. Furthermore, the measurement accuracy for these methods depends on the expertise of the operator.

To overcome the problems occurred in traditional leaf area measurement method, several alternative methods for leaf area measurement have been proposed. Córcoles, et al. [6] and Amiri and Shabani [7] have proposed semi-automatic methods for measuring leaf area. They manually measured the length and width of leaf and inputted the results to a computer program for estimating leaf area using general linear regression model (GLM) [6] and adaptive neural-based fuzzy inference system (ANFIS) [7]. The methods have been validated using several types of leaves and produced high coefficient of determination. However, the accuracy of the methods is very dependent on the expertise of the operator in measuring length and width manually.

Gong, et al. [2], Lü, et al. [3], Patil and Bodhe [4], and Radzali, et al. [5] have been proposed automatic methods to measure leaf area by utilizing image processing technique. To measure leaf area, the proposed methods captured the image of measured leaf and an object reference with known area together using a camera. The image was then processed to obtain a binary image. Leaf area was calculated by comparing the number of leaf pixels and the number of object reference pixels in the binary image and then multiplying the result with actual object reference area. The proposed methods have been validated and produced low error. However, the using of object reference could lead a problem during segmentation process and finally could decrease measurement accuracy. In addition, the method

proposed by Gong, et al. [2] was not fully automatic; the user intervention was still needed during segmentation process.

Therefore, an automatic leaf area measurement method which does not need object reference and user intervention need to be developed. A synergy between image processing technique and artificial neural network (ANN) can be considered for solving the problems. ANN is a nonlinear model that imitates human nervous system and has simple computation [8]. ANN has been applied to solve classification and prediction problems in several areas, such as natural produce recognition using computer vision [9], egg volume measurement using computer vision [10], biodiesel production optimization [11], and gas concentration estimation for electronic nose [12].

This paper proposes an image based leaf area measurement method using ANN. The proposed method uses length, width, area, and perimeter of leaf extracted from the image of measured leaf and used the features as input to ANN for predicting leaf area. Therefore the proposed method can be used to measure leaf area without object reference and user intervention. The rest of the paper is arranged as follow. Section 2 explains the material and the detail of all steps used in the proposed method. Section 3 describes the experimental setup for validating the proposed method. Section 4 presents experimental results and discussion. Finally, conclusion is drawn in Section 5.

II. MATERIALS AND METHOD

A. Materials

Hardware used in the proposed method consisted of a camera, two flat acrylic boards, an USB cable, and a computer, as shown in Fig. 1. A Logitech® HD Webcam c270h was used to capture the image of measured leaf. The camera was located on the above of measured leaf at a distance of 50 cm with an orientation such that the image plane is parallel to leaf surface and connected to the computer using the USB cable.

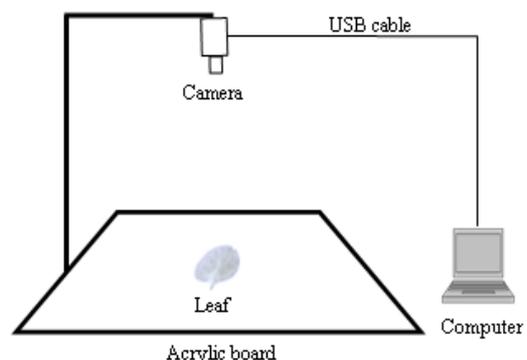


Fig. 1. Hardware used in the proposed leaf area measurement method.

To flatten the measured leaf, the leaf was placed between two flat acrylic boards. The lower board was white painted and used as background during image acquisition. The proposed system employed a 2.20GHz Intel Core 2 portable computer with RAM 4GB and Windows 7 operating system to control the camera, process the acquired image, and measure leaf area.

To validate the proposed method, 30 samples of leaf were chosen randomly from an area around Universitas Surabaya. The samples consisted of 10 kailan (*Brassica oleracea* Alboglabra Group) leaves, 10 ipecac (*Cephaelis ipecacuanha*) leaves, and 10 wild betel (*Piper sarmentosum* Roxb. Ex Hunter) leaves. The exact area of all samples were measured manually using paper weighing method [1].

B. Method

The proposed leaf area measurement method consisted of a series steps starting from image acquisition followed by preprocessing, segmentation, features extraction, and leaf area estimation. The details for every step are explained in the following subsections.

1) Image Acquisition

The measured leaf was located between two flat acrylic boards during image acquisition. The image of measured leaf was captured using the camera with a white background. The white background was chosen since in general the color of leaf is different from white. Therefore leaf pixels could be easily separated from background pixels during segmentation step. The image was captured in RGB color space and was then saved in PNG file for further process. Every leaf sample was captured twice in vertical and horizontal directions. The examples of captured image are shown in Fig. 2.

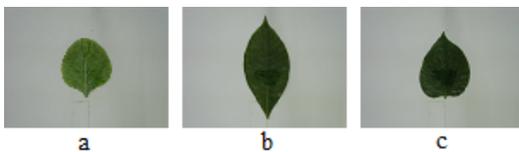


Fig. 2. The examples of captured image: (a) kailan, (b) ipecac, (c) wild betel.

2) Preprocessing

In preprocessing step, the captured image was converted from image in RGB color space to gray scale image by calculating the weighted average of R, G, and B values for every pixel in the captured image. To reduce noises produced by the camera, a 5×5 Gaussian filter [13] was applied to the gray scale image. Fig. 3 shows the example of preprocessing result.

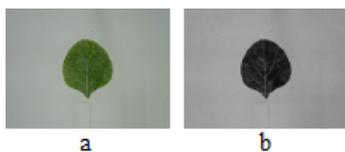


Fig. 3. The example of preprocessing result: (a) captured image, (b) gray scale image.

3) Segmentation

Segmentation step was used to separate leaf pixels from background pixels in the gray scale image. The proposed method employed thresholding method [13] in this step. The

threshold value T was automatically determined using Otsu method [14]. As can be seen in Fig. 3 (b), the intensity of leaf pixel in the gray scale image was less than the intensity of background pixel; therefore a pixel in the gray scale image with intensity less than T was categorized as leaf pixel with binary value 1 (white pixel), otherwise as background pixel with binary value 0 (black pixel). The result of segmentation step was a binary image, as shown in Fig. 4.



Fig. 4. The example of segmentation result: (a) captured image, (b) binary image.

4) Features Extraction

In this step, four features were extracted from leaf pixels in the binary image. The extracted features were used to estimate the area of measured leaf in the next step. The features were length, width, area, and perimeter.

- Length (L) was defined as the length (in pixels) of major axis of measured leaf. The major axis was defined as line connecting between two pixels on the leaf boundary that have the longest distance in the binary image, as shown in Fig. 5 (a).
- Width (W) was defined as the length (in pixels) of minor axis of measured leaf. The minor axis was defined as line connecting between two pixels on the leaf boundary that perpendicular to the major axis in the binary image, as shown in Fig. 5 (b).
- Area (A) was defined as the number of leaf pixels (white pixels) in the binary image, as shown in Fig. 5 (c).
- Perimeter (P) was defined as the number of pixels on the leaf boundary in the binary image, as shown in Fig. 5 (d).



Fig. 5. The extracted features: (a) length, (b) width, (c) area, (d) perimeter

5) Leaf Area Estimation

To estimate the area of measured leaf, the proposed method used an artificial neural network based on the features extracted in the previous step. The architecture of ANN consisted of three layers, which are an input layer, a hidden layer, and an output layer. The output layer had one neuron that corresponds to leaf area. The number of neurons in the input layer depended on the number of features used to estimate the area of measured leaf. To obtain high leaf area estimation accuracy, a feature selection was performed by inputting all possible combination of features to ANN. Therefore, there were 15 ANNs with different input. The number of neurons in the hidden layer was heuristically determined in the range of 2 and 5 in an experiment such that the ANN produces high leaf area estimation accuracy.

The ANN used hyperbolic tangent sigmoid, as in (1), and linear functions, as in (2), as transfer functions from the input layer to the hidden layer and from the hidden layer to the output layer, respectively. The ANN was trained using back propagation algorithm [15] with mean square error (MSE) used as performance function. All features were scaled to $[-1,1]$ before training process to avoid the domination of a feature against the others and to speed up training process [9].

$$f(x) = \frac{1 - e^{-2x}}{1 + e^{-2x}} \quad (1)$$

$$f(x) = x \quad (2)$$

III. EXPERIMENTAL SETUP

To validate the proposed method, an experiment has been conducted in laboratory. In the experiment every leaf sample was captured twice in vertical and horizontal direction. Therefore, there were 20 leaf images from every type of leaf or there were 60 images data in total.

Five-fold cross validation was used to develop training and testing data from 60 leaf images [16]. All images data were randomly divided into five mutually exclusive sub data with equal size. One of sub data was used as testing data and 4 remaining sub data were used as training data. This process was repeated 5 times such that every sub data is used as testing data once.

In every training process, ANN was trained with 15 different input combinations and the different number of nodes in hidden layer. MSE between the exact area and its estimation was calculated for testing data to measure the accuracy of ANN in every training process. ANN with the lowest MSE was then used in the proposed method. In addition the training time was also considered in determining the best ANN.

Furthermore, the proposed method was used to measure the leaf area of all samples. Absolute relative error (ARE) between the exact area and the area measured using the proposed method was calculated for all samples to measure the accuracy of the proposed method. ARE was calculated using (3),

$$ARE = \frac{|A_E - A_P|}{A_E} \times 100\% \quad (3)$$

where A_E and A_P are the exact area and the area measured using the proposed method, respectively.

IV. RESULT AND DISCUSSION

The proposed method was implemented in a software using Visual C++ 2010 with open source computer vision library OpenCV 231 [17]. The software was used in the experiment to measure the leaf area of all samples. The experiment results are explained in the following sub sections.

A. The Architecture of ANN

The results of feature selection and determining the number of hidden nodes in the hidden layer experiments are summarized in TABLE I. As can be seen in TABLE I. The

higher accuracy with average MSE of 0.249 was achieved if ANN used W , A , and P as input features and three nodes in the hidden layer, shown in TABLE I. The training time for such ANN architecture was 2.983 s. From TABLE I, it can also be seen that the second higher estimation accuracy with average MSE of 0.251 was obtained if ANN used L and A as input features and four nodes in the hidden layer. However, by using this architecture, there was an increase in training time of 1.504 s.

TABLE I. THE RESULTS OF FEATURE SELECTION AND DETERMINING THE NUMBER OF HIDDEN NODES IN THE HIDDEN LAYER EXPERIMENTS

The Number of Nodes in Hidden Layer	Average MSE			
	2	3	4	5
Input Features				
L	34.562	35.786	30.901	25.443
W	148.050	117.069	121.946	122.131
A	0.536	0.398	0.355	1.160
P	11.224	15.888	13.500	12.737
L, W	1.386	1.293	1.063	0.956
L, A	0.345	0.340	0.251	0.279
L, P	11.186	19.587	10.649	10.768
W, A	0.347	0.669	0.352	0.271
W, P	2.632	2.170	3.295	2.667
A, P	0.554	0.255	0.349	0.299
L, W, A	0.357	0.380	0.510	0.344
L, W, P	1.251	1.384	1.311	1.173
L, A, P	0.476	0.337	0.274	0.449
W, A, P	0.401	0.249	0.341	0.384
L, W, A, P	0.471	0.341	0.308	0.277

Based on these results, the proposed method employed two ANN architectures to estimate leaf area. The first architecture consisted of an input layer with two input nodes correspond to L and A features, a hidden layer with four nodes and an output layer with one node correspond to leaf area, as shown in Fig. 6. The second architecture consisted of an input layer with three input nodes correspond to W , A , and P features, a hidden layer with three nodes and an output layer with one node correspond to leaf area, as shown in Fig. 7.

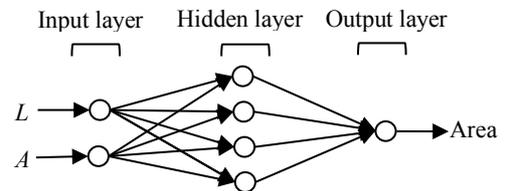


Fig. 6. The first ANN architecture used in the proposed method

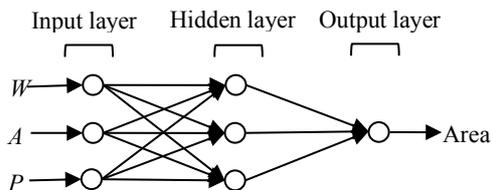


Fig. 7. The second ANN architecture used in the proposed method

B. Leaf Area Measurement

The results of leaf area measurement experiment for all samples using the proposed method with the first and the second ANN architectures are summarized in TABLE II and TABLE III, respectively. As can be seen in TABLE II and TABLE III, on average leaf area measured using the proposed method with the first and the second ANN architectures closed to exact leaf with mean ARE less than 1%. This results show that the proposed method has high measurement accuracy in measuring leaf area of all samples.

TABLE II. THE MEASUREMENT RESULTS USING THE PROPOSED METHOD WITH THE FIRST ANN ARCHITECTURE

Leaf Sample	Average Area(cm ²)		Mean ARE (%)
	Exact	Proposed method	
Kailan	29.996	30.060	0.783
Ipecac	52.809	52.939	0.586
Wild betel	36.896	36.869	0.939
All samples	39.900	39.956	0.769

TABLE III. THE MEASUREMENT RESULTS USING THE PROPOSED METHOD WITH THE SECOND ANN ARCHITECTURE

Leaf sample	Average Area(cm ²)		Mean ARE (%)
	Exact	Proposed method	
Kailan	29.996	29.912	0.635
Ipecac	52.809	52.802	0.301
Wild betel	36.896	37.000	0.871
All samples	39.900	39.905	0.602

For both ANN architectures, the lowest and highest mean ARE were achieved by the proposed method in measuring ipecac and wild betel leaves, respectively. The proposed method with the first ANN architecture produced mean ARE of 0.7796%. On the other hand, with the second ANN architecture the proposed method produced lower mean ARE, which is 0.602%. Based on this condition, it can be inferred that by employing the second ANN architecture the proposed method produce more accurate leaf area measurement result.

For further analysis, the linear relationship between leaf area measured using the proposed method and exact leaf area was also investigated. Fig. 8 and Fig. 9 show this linear relationship for the first and the second ANN architectures, respectively. It can be seen in Fig. 8 and Fig. 9, leaf area measured using the proposed method and exact leaf area had

high linear relationship with coefficient of determination (R^2) greater than 0.99 for both ANN architectures. It means that more than 99% variation in the exact leaf area can be explained by a linear relationship with leaf area measured using the proposed method. From computational time point of view, the proposed method only needed less than 0.1 s for measuring area of a leaf.

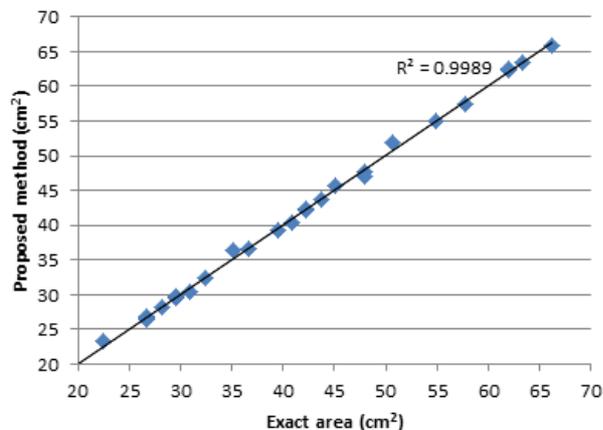


Fig. 8. The linear relationship between exact area and area measured using the proposed method with the first ANN architecture

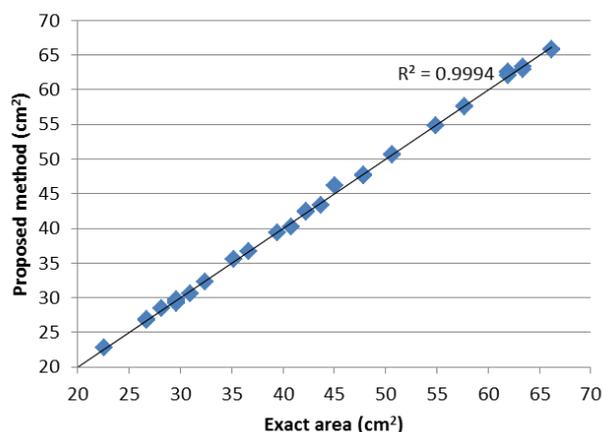


Fig. 9. The linear relationship between exact area and area measured using the proposed method with the second ANN architecture

V. CONCLUSION

An image based method for measuring leaf area using artificial neural network (ANN) is proposed in this paper. The method used a camera to capture the image of measured leaf from the distance of 50 cm. The image was processed to produce a binary image. From the binary image, four features were extracted and used as input to ANN for estimating leaf area. The proposed method has been tested using three types of leaf, including kailan, ipecac, and wild betel in an experiment. The experiment results show that the proposed method has high measurement accuracy compared to exact area with mean absolute relative error less than 1%. In addition, leaf area measured using the proposed method has high linear relationship with exact leaf area. Therefore the proposed method can be considered as alternative for manual measurement method in measuring leaf area. For future study, the application of the proposed method in plant growth monitoring needs to be investigated.

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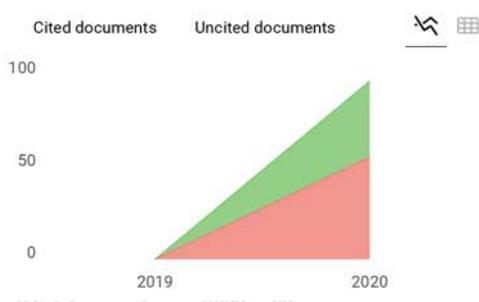
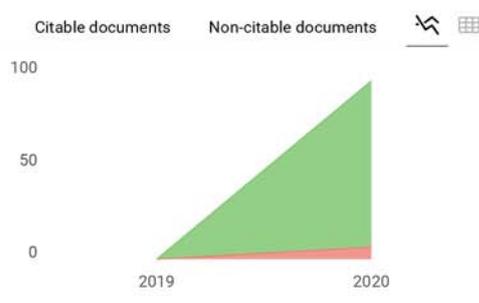
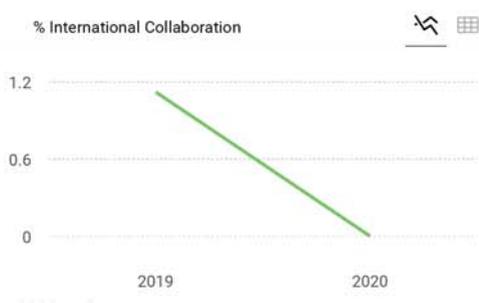
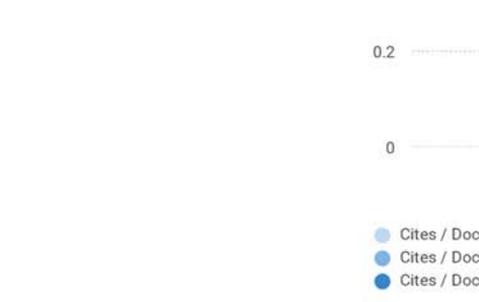
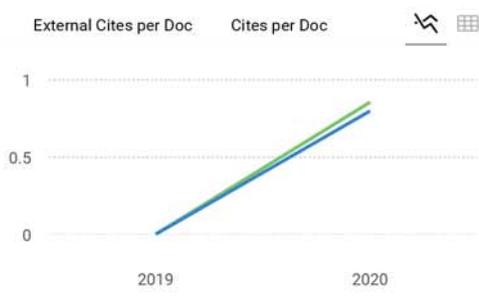
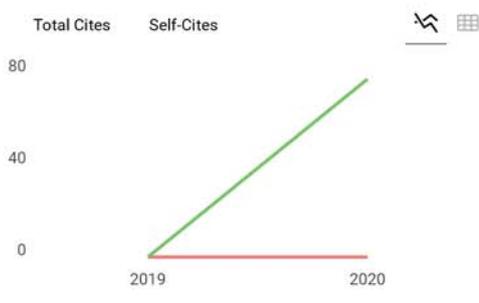
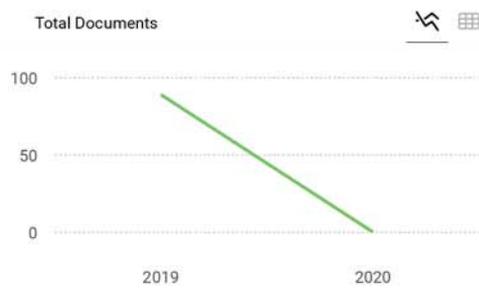
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Papers in International Conference of Artificial Intelligence and Information Technology 2019 for media communication only which is spread among the authors, Keynote speakers, and other academic colleagues in the International Conference of Artificial Intelligence and Information Technology 2019, at 13-14 March 2019 at Platinum Adisucipto Hotel & Conference Center, Yogyakarta, Indonesia.

Each paper which is shown in this International Conference of Artificial Intelligence and Information Technology 2019 can be appeared at proceeding of International Conference of Artificial Intelligence and Information Technology 2019 where the authors of each paper should :

1. Present their paper
2. Submit the paper's revision to icaiit.reg@uajy.ac.id

Failing to do the requirement will be subjected to eliminated from proceeding of International Conference of Artificial Intelligence and Information Technology 2019.

International Conference of Artificial Intelligence and Information Technology 2019 Conference Schedule

Wednesday, 13 March 2019

Time	Activity		
08.00 - 09.00	Participants Registration & Materials Collection		
09.00 - 10.00	Welcome Speech & Opening Ceremony - General Chair of ICAIIT 2019 - Rector Kalbis Institute - Rector Universitas Atma Jaya Yogyakarta		
10.00 - 10.30	Coffee Break		
10.30 - 11.15	Keynote Speech 1 Professor Andrea Corradini (Copenhagen School of Design and Technology, Denmark) Speech Title: Multimodal Data Analysis		
11.15 - 12.00	Keynote Speech 2 HAIYONG WU, Ph. D (School of Information Engineering, Nanjing Xiaozhuang University) Speech Title: Deep Learning in Tractography		
12.00 - 13.00	Lunch		
13.00 - 15.00 (15 Minutes presentation per paper) Session 1: 1:13.00-13.15 2:13.15-13.30 3:13.30-13.45 4:13.45-14.00	Titanium 1 1. 1570508359 2. 1570526507 3. 1570526480 4. 1570526013 5. 1570518440 6. 1570519077 7. 1570518796	Titanium 2 1. 1570512443 2. 1570512569 3. 1570514049 4. 1570507038 5. 1570512457 6. 1570526214 7. 1570513290	Titanium 3 1. 1570512696 2. 1570512578 3. 1570512583 4. 1570512614 5. 1570512722 6. 1570512735 7. 1570518672

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15.00 - 15.30	Coffee Break			
15.30 - 17.00 (15 Minutes presentation per paper) Session 2: 1:15.30-15.45 2:15.45-16.00 3:16.00-16.15 4:16.15-16.30 5:16.30-16.45 6:16.45-17.00	Titanium 1 1.1570515432 2.1570526222 3.1570526304 4.1570526319 5.1570526544 6.1570526452	Titanium 2 1.1570513614 2.1570497900 3.1570497821 4.1570512658 5.1570523975 6.1570525893	Titanium 3 1.1570526455 2.1570526552 3.1570516699 4.1570513732 5.1570509093 6.1570526401	Ballroom 1 1. 1570521650 2. 1570526538 3. 1570526466 4. 1570526453 5. 1570524081 6. 1570513593
18.00 - 20.00	Gala Dinner at Rama Shinta Resto Prambanan Temple			

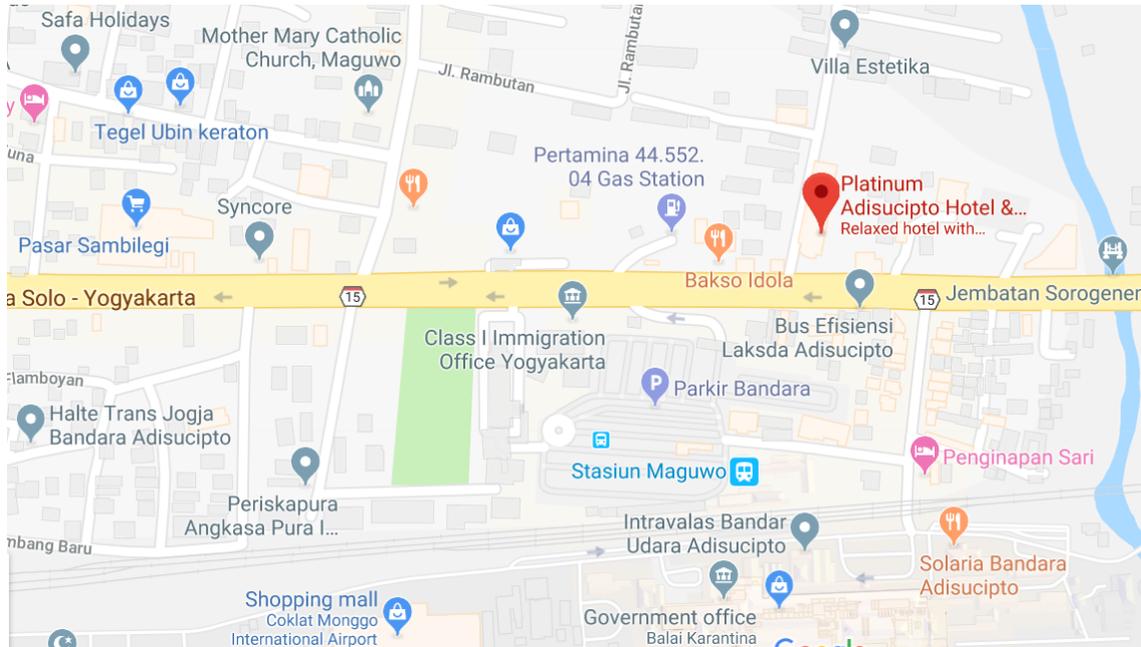
Thursday, 14 March 2019

Time	Activity			
08.00 - 09.00	Registration & Coffee Break			
09.00 - 09.45	Keynote Speech 3 Dr. Suryadiputra Liawatimena, S.Kom., PgDip.App.Sci (Universitas Bina Nusantara, Indonesia) Speech Title: Artificial Intelligence in Agriculture & Fishery			
09.45 - 10.30	Keynote Speech 4: Associate Professor Władysław Homenda (Warsaw University of Technology, Poland) Speech Title: Cognitive Maps for Time Series Modeling			
10.30 - 11.30 (15 Minutes presentation per paper) Session 3: 1:10.30-10.45 2:10.45-11.00 3:11.00-11.15 4:11.15-11.30	Titanium 1 1.1570526412 2.1570526525 3.1570516332 4.1570526533	Titanium 2 1. 1570526555 2. 1570526750 3. 1570508178 4. 1570526557	Ballroom 1 1. 1570526547 2. 1570526500 3. 1570511011 4. 1570522671	Ballroom 2 1. 1570526541 2. 1570512562 3. 1570513741 4. 1570513710
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15.00 - 15.30	Coffee Break			

15.30 - 16.30	Closing Ceremony
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Friday, 15 March 2019

Time	Activity
07.00 - 20.00	Excursion (for Full Package only)



International Conference of Artificial Intelligence and Information Technology 2019 List of Papers

Paper Code	Paper Title (Authors)	Room (Session) Time	Page
1570484576	A Comparative Study on Variational Autoencoders and Generative Adversarial Networks (Mirza Sami, Iftekharul Mobin)	Titanium 1 (4), 14.00-14.15	1
1570497821	Face Detection using Haar Cascades to Filter Selfie Face Image on Instagram (Adri Priadana, Muhammad Habibi)	Titanium 2 (2), 16.00-16.15	6
1570497875	MREAK : Morphological Retina Keypoint Descriptor (Himanshu Vaghela, Manan Oza, Sudhir Bagul)	Ballroom 1 (4), 12.45-13.00	10
1570497900	Semi-Supervised Image-to-Image Translation (Manan Oza, Himanshu Vaghela, Sudhir Bagul)	Titanium 2 (2), 15.45-16.00	16
1570507038	Social Media Prototyping for Web-based Property Business (Harya Bima Dirgantara, Paramaresthi Windriyani, Rendy Adiwikarta)	Titanium 2 (1), 13.45-14.00	21
1570508178	Simple Implementation of Fuzzy Controller for Low Cost Microcontroller (Wakhyu Dwiono, Arif Johar Taufiq, W Winarso)	Titanium 2 (3), 11.00-11.15	26
1570508359	Design of Manufacture Professional Training and Assessment Information System in The Implementation of PBET (Production Based Education and Training) Learning Activity Model (Yustina Tritularsih)	Titanium 1 (1), 13.00-13.15	31
1570509093	Extraction of Skull and Face Surfaces from CT Images (Masy Ari Ulinuha, Eko Mulyanto Yuniarno, I Ketut Eddy Purnama, Mochamad Hariadi)	Titanium 3 (2), 16.30-16.45	37
1570510791	Real-time Moving Object Video Tracking using Support Vector Machines for Visual Servo Application (Modestus Oliver Asali, Saripudin, Bambang Trilaksono, Toto Indriyanto)	Titanium 2 (4), 13.00-13.15	41
1570510797	Visual Servoing using Mixed Sensitivity H_{∞} Control for Yaw-Pitch Camera Platform (Saripudin, Modestus Oliver Asali, Bambang Riyanto Trilaksono, Toto Indriyanto)	Titanium 2 (4), 12.45-13.00	48
1570511011	Automatic Lecture Video Content Summarization with Attention-based Recurrent Neural Network (Muhammad Bagus Andra, Tsuyoshi Usagawa)	Ballroom 1 (3), 11.00-11.15	54
1570511144	Design and Development Meeting Schedule Management Application using the RAD Method (Egia Rosi Subhiyakto, Yani Parti Astuti)	Titanium 1 (4), 14.15-14.30	60
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1570512443	The Priority of Tourism Destinations Development using 6AsTD Framework and TOPSIS (Yunifa Miftachul Arif, Supeno Mardi Susiki Nugroho, Mochamad Hariadi)	Titanium 2 (1), 13.00-13.15	70
1570512457	Systematic Literature Review of Profiling Analysis Based on Social Media (Mihundayani, Ema Utami, Anggit Dwi Hartanto, Sumarni Adi, Suwanto Raharjo)	Titanium 2 (1), 14.00-14.15	77
1570512562	NDNization of IP Network Based On Communication Flow Model (Fandhy Bayu Rukmana, Nina Hendrarini, Riri Fitri Sari)	Ballroom 2 (3), 10.45-11.00	83
1570512569	Improve Smart Waste Management to Preserve Tourist Attractions Yogyakarta in IoT Environment (RANIA RIZKI ARINTA, Dominikus Boli Watomakin, Suyoto)	Titanium 2 (1), 13.15-13.30	88
1570512578	Smart Kost: Ubiquitous Boarding House Controlling and Monitoring System in Industry 4.0 (Julius Galih Prima Negara, Alfredo Gormantara, Suyoto)	Titanium 3 (1), 13.15-13.30	94
1570512583	IoT Based: Improving Control System For High-Quality Beef in Supermarkets	Titanium 3 (1), 13.30-13.45	99

	(BALTRA AGUSTI PRAMAJURI, Erni Widarti, Suyoto)		
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1570512694	Determining the Neural Network Topology from the Viewpoint of Kuhn's Philosophy and Popper's Philosophy (MUHAMMAD IBNU CHOLDUN RACHMATULLAH, Kridanto Surendro, Judhi Santoso, Dimitri Mahayana)	Ballroom 1 (4), 12.30-12.45	115
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1570512722	IoT Based: Hydroponic Using Drip Non-Circulation System for Paprika (Dhana Sudana, Dadang Eman, Suyoto)	Titanium 3 (1), 14.00-14.15	124
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1570513741	REINFORCEMENT POINT AND FUZZY INPUT DESIGN OF FUZZY Q-LEARNING FOR MOBILE ROBOT NAVIGATION SYSTEM (Arga Dwi Pambudi, Trihastuti Agustinah, Rusdhianto Efendi Abdul Kadir)	Ballroom 2 (3), 11.00-11.15	186
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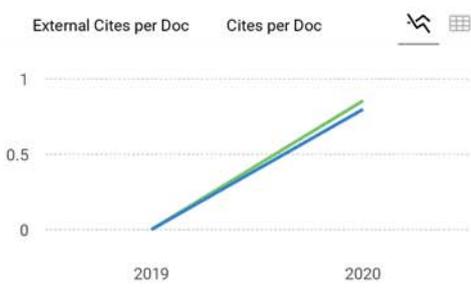
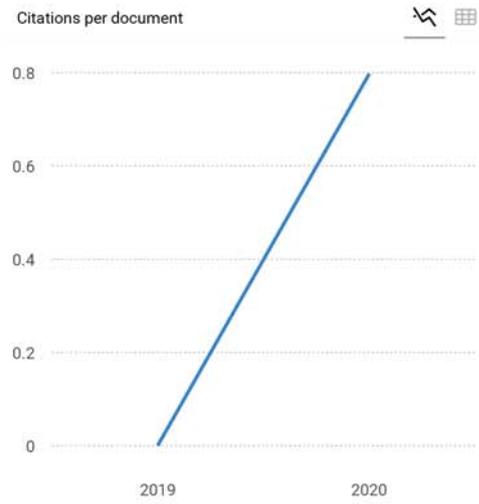
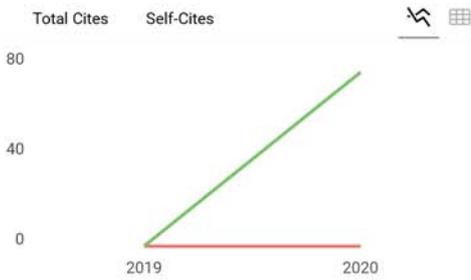
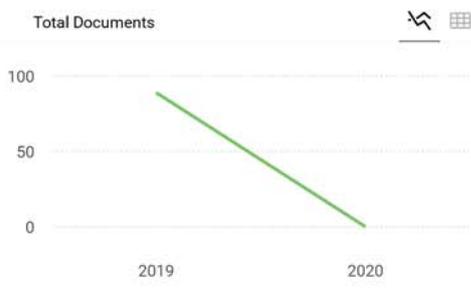
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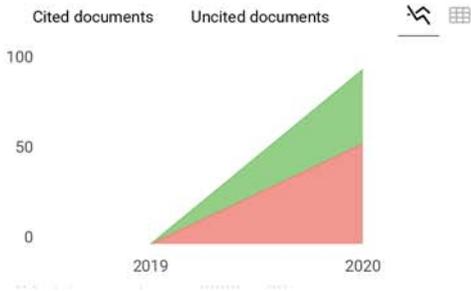
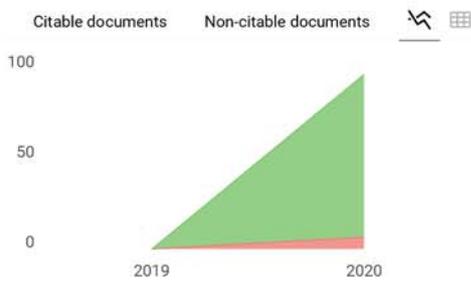
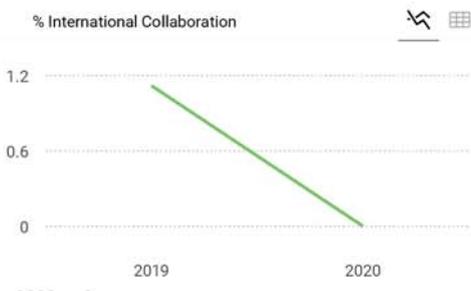
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Abstract

Leaf area is an important parameter in plant monitoring. An automatic method for measuring leaf area is needed to obtain accurate result. In this paper, a method for automatic leaf area measurement from image is proposed. The method captured the image of leaf without object reference. Four features were extracted from the image and used as input to artificial neural network for estimating leaf area. The experiment results show that the proposed method can measure leaf area with mean absolute relative error less than 1% and less computational time. © 2019 IEEE.

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